Classical & Quantum Algorithms for Hamiltonian Simulation

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CQIF Seminar, Cambridge

Solution of the Schrödinger equation,

 $\mathrm{i}\partial_t\psi\ =\ \mathrm{H}(t)\,\psi,\qquad \mathrm{H}(t)^*=\mathrm{H}(t),\qquad \psi(t)\in\mathscr{H}.$

Feynman, R. P. Simulating physics with computers. Int J Theor Phys 21, 467-488 (1982).

the real difficulty is this: If we had many particles, we have R particles, for example, in a system, then we would have to describe the probability of a circumstance by giving the probability to find these particles at points x_1, x_2, \ldots, x_R at the time t. That would be a description of the probability of the system. And therefore, you'd need a k-digit number for every configuration of the system, for every arrangement of the R values of x. And therefore if there are N points in space, we'd need N^R configurations.

n-body problems

- PDE, $\psi \in \mathbb{C}^{N^{3n}}$ after spatial discretisation with N points in each direction,
- ODE, $\psi \in \mathbb{C}^{2^n}$ for 2-level systems (e.g. spin systems).

4. QUANTUM COMPUTERS—UNIVERSAL QUANTUM SIMULATORS

The first branch, one you might call a side-remark, is, Can you do it with a new kind of computer—a quantum computer? (I'll come back to the other branch in a moment.) Now it turns out, as far as I can tell, that you can simulate this with a quantum system, with quantum computer elements.



- · Linear growth in number of qubits vs exponential in classical computing
- Provides a straightforward approach for beating the curse of dimensionality in quantum physics and chemistry simulations

• A uniquely quantum phenomenon that has no classical counterpart.



$$\begin{split} \rho &= \frac{1}{2}(I + \boldsymbol{s} \cdot \boldsymbol{\sigma}) \in \mathbb{C}^{2 \times 2}, \\ & \boldsymbol{s} \in \mathbb{R}^{3}, \\ & \text{and } \boldsymbol{\sigma} = (X, Y, Z) \end{split}$$

are 2×2 Pauli matrices.

- The phenomenon that powers
 - magnetic resonance imaging (MRI)
 - spintronics
 - quantum computing
- Responsible for ferromagnetism.
- Suspected to be involved in detection of Earth's magnetic field by birds (quantum biology).
- Fay, Lindoy, Manolopolous, Hore 2020: 'the accurate simulation of anisotropic magnetic field effects relevant to magnetoreception seems to require full quantum mechanical calculations'

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Resurgence of interest in quantum algorithms for Hamiltonian simulation.

Berry et al. 15, Low & Chuang 17, 19, Low & Wiebe 18, Smith et al. 19, Kieferova et al. 19, Berry et al. 20, Chen et al. 21, Haah et al. 21, Jin & Li 21, Jin et al. 21, Dong et al. 21,22, An et al. 22, Watkins et al. 22, Mizuta et al. 23,...

Hamiltonian simulation of two-level systems is among early candidates for demonstrating quantum advantage. (Childs et al. 18, Seetharam et al. 21).

- Claim by IBM (14 June 2023): Kim, Eddins, Anand, Wei, van den Berg, Rosenblatt, Nayfeh, Wu, Zaletel, Temme & Kandala (2023), 'Evidence for the utility of quantum computing before fault tolerance', Nature 618, 500–505.
- Claim by DWave (1 March 2024): King et al, 'Computational supremacy in quantum simulation', arXiv:2403.00910



- Every gate has an underlying Hamiltonian
- Every quantum circuit is a Hamiltonian Simulation (except measurement)
- Due to the unitary nature of quantum computing, Hamiltonian simulation is a natural building block for quantum algorithms
- Important subroutine in quantum algorithms QPE (Kitaev 95), HHL (Harrow, Hassidim, Lloyd 09)

Outline

Hamiltonian Simulation

$$\mathrm{i}\partial_t\psi\ =\ \mathrm{H}(\psi,t)\,\psi,\qquad \psi(t)\in\mathscr{H}.$$

1. Linear

2. Driven

 $\partial_t u = A u$ $\partial_t u = A(t) u$

3. Non-linear

 $\partial_t u = \mathbf{A}u + \mathbf{N}(u)$

The Schrödinger equation

$$\partial_t u = -\mathrm{i}\mathrm{H}u, \qquad u(0) = u_0, \qquad \mathrm{H}^* = \mathrm{H},$$

can be thought of as an ODE

$$\partial_t u = \mathcal{A} u, \qquad u(0) = u_0, \qquad \mathcal{A} = -\mathrm{i}H$$

The exact solution of this ODE is given by the matrix exponential

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exp maps Lie algebra $iH \in \mathfrak{su}(n)$ to Lie group $e^{-itH} \in U(n)$, leading to:

Unitary evolution

$$\langle u(t), v(t) \rangle = \langle u(0), v(0) \rangle$$

Conservation of norm

$$\|u(t)\|_2 = \|u(0)\|_2 = 1$$

Conservation of energy

 $\langle u(t), \mathrm{H}u(t) \rangle = \langle u(0), \mathrm{H}u(0) \rangle$

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Geometric Numerical Integration:

The design of numerical methods that conserve certain properties exactly, even if numerical error in solution is finite

Computing e^A or $e^A u_0$

C. Moler & C. V. Loan, Nineteen Dubious Ways to Compute the Exponential of a Matrix, Twenty-Five Years Later, SIAM Review (2003).

	Diagonalisation	Scaling and Squaring	Splitting
lf	$A = UDU^*$	A > 1	$A = \mathbf{B} + C$
	$e^{A} = U e^{D} U^{*}$	$\mathbf{e}^{A} = \left(\mathbf{e}^{A/n}\right)^{n}$	$\mathbf{e}^{A} = \lim_{n \to \infty} \left(\mathbf{e}^{B/n} \mathbf{e}^{C/n} \right)^{n}$
Fast when	Uu_0 and U^*u_0 cheap	$\ A\ < 1$ needed	$e^{\pmb{B}}, e^{\pmb{C}}$ cheap

	Asymptotic	Approximate e ^z on spectrum	Iterative
	z ightarrow 0	$z \in [a, b] \subseteq \sigma(A)$	Use A and u0
	Taylor	Chebyshev	
Polynomial	$\sum_{k=0}^{n} \frac{z^k}{k!}$	$J_0(i) + 2 \sum_{k=1}^{n} i^k J_k(-i) T_k(z)$	Polynomial Krylov
Rational	$\frac{Padé}{\frac{1+\frac{1}{2}z+\frac{1}{12}z^2}{1-\frac{1}{2}z+\frac{1}{12}z^2}}$?	Rational Krylov

$\textbf{Trotterisation} \leftrightarrow \textbf{Splitting methods for matrix exponential}$

lf e	hA	and	e ^{hB}	are	easier	to	compute,	approximate	$e^{h(A+B)}$	by
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splitting	error	name	stages
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$\mathrm{e}^{a_1hB}\mathrm{e}^{b_1hA}\mathrm{e}^{a_2hB}\cdots\mathrm{e}^{b_nhA}\cdots\mathrm{e}^{a_2hB}\mathrm{e}^{b_1hA}\mathrm{e}^{a_1hB}$	$\mathcal{O}(h^{2p+1})$	Classical	$\mathcal{O}(2^p)$

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$e^{\frac{h}{6}A}e^{\frac{h}{2}B}e^{\frac{2}{3}(hA+\frac{h^3}{48}[[A,B],B])}e^{\frac{h}{2}B}e^{\frac{h}{6}A}$	$\mathcal{O}(h^{2p+1})$	Compact	$\mathcal{O}(2^p)$
$\mathrm{e}^{\frac{h}{2}B}\mathrm{e}^{\frac{h}{2}A}\mathrm{e}^{h^3R}\mathrm{e}^{h^5S}\mathrm{e}^{h^3R}\mathrm{e}^{\frac{h}{2}A}\mathrm{e}^{\frac{h}{2}B}$	$\mathcal{O}(h^{2p+1})$	Asymptotic	$\mathcal{O}(p)$

Yoshida 1990, Murua & Sanz-Serna 1999, Chin & Chen 2002, McLachlan & Quispel 2002, Omelyan, Mrygold & Folk 2003, Blanes, Casas & Murua 2008, Chartier & Murua 2009, ... Asymptotic (Zassenhaus) Bader, Iserles, Kropielnicka, & S. 2014, Found. Comp. Math.

If e^{hA} and e^{hB} conserve unitarity, then splitting conserves unitarity, norm, modified energy.

Example: Spin Hamiltonians



$$\mathcal{H} = \underbrace{\mathbf{e}^{\top} \mathbb{S}}_{\mathcal{H}_{ss}(t)} + \underbrace{\frac{1}{2} \mathbb{S}^{\top} \mathbf{C} \mathbb{S}}_{\mathcal{H}_{in}}$$
$$= \sum_{k=1}^{n} \sum_{\alpha \in \{X, Y, Z\}} e_{k}^{\alpha} \alpha_{k} + \frac{1}{2} \sum_{j, k=1}^{n} \sum_{\alpha, \beta \in \{X, Y, Z\}} \mathbf{C}_{j, k}^{\alpha, \beta} \alpha_{j} \beta_{k}$$

where α_k acts on kth spin only,

$$\alpha_k = \underbrace{I \otimes \cdots \otimes I}_{n-k \text{ times}} \otimes \underbrace{\alpha}_{k\text{th}} \otimes \underbrace{I \otimes \cdots \otimes I}_{k-1 \text{ times}} \in \mathbb{C}^{2^n \times 2^n},$$

and $\alpha = X, Y, Z$ are Pauli matrices,

$$X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad Y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Two-level systems: Ising chains, Kitaev models, NMR/ESR, qubits (spin, superconducting, ...)

 $\partial_t u = \mathcal{A} u, \quad u(0) = u_0,$

exact solution given by matrix exponential

$$u(t) = \exp(t\mathcal{A})u_0 = \sum_{k=0}^{\infty} \frac{(t\mathcal{A})^k}{k!}u_0.$$

Hamiltonian simulation:

$$\mathcal{A} = -i \left(\mathbf{e}^{\mathsf{T}} \mathbb{S} + \frac{1}{2} \mathbb{S}^{\mathsf{T}} \mathcal{C} \mathbb{S} \right)$$
(1)

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For non-interacting spins, since $\mathfrak{su}(2)$ is spanned by iX, iY, iZ and

$$[X, Y] = iZ, \quad [Y, Z] = iX, \quad [Z, X] = iY,$$

can compute exponential analytically

$$\mathbf{e}^{t\mathcal{A}} = \bigotimes_{k=1}^{n} \mathbf{e}^{-\mathbf{i}t\mathbf{e}_{k}\cdot\boldsymbol{\sigma}} = \bigotimes_{k=1}^{n} \left(\begin{array}{c} \cos\left(\frac{t\|\boldsymbol{e}_{k}\|}{2}\right) - \mathbf{i}\mathbf{e}_{k}^{z} \frac{\sin\left(\frac{t\|\boldsymbol{e}_{k}\|}{2}\right)}{\|\mathbf{t}\mathbf{e}_{k}\|} & (-\mathbf{i}\mathbf{e}_{k}^{x} - \mathbf{e}_{k}^{y}) \frac{\sin\left(\frac{t\|\boldsymbol{e}_{k}\|}{2}\right)}{\|\boldsymbol{e}_{k}\|} \\ (-\mathbf{i}\mathbf{e}_{k}^{x} + \mathbf{e}_{k}^{y}) \frac{\sin\left(\frac{t\|\boldsymbol{e}_{k}\|}{2}\right)}{\|\boldsymbol{e}_{k}\|} & \cos\left(\frac{t\|\boldsymbol{e}_{k}\|}{2}\right) + \mathbf{i}\mathbf{e}_{k}^{z} \frac{\sin\left(\frac{t\|\boldsymbol{e}_{k}\|}{2}\right)}{\|\boldsymbol{e}_{k}\|} \end{array} \right),$$

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Trotterisation: For -iH = A + B we need to split

$$\exp(h(A+B)) = e^{hA}e^{hB} + \mathcal{O}(h^2)$$

NA

Trotterisation:

$$\mathrm{e}^{-\mathrm{i} h (\mathcal{H}^X + \mathcal{H}^Y + \mathcal{H}^Z)} = \mathrm{e}^{-\mathrm{i} h \mathcal{H}^X} \mathrm{e}^{-\mathrm{i} h \mathcal{H}^Y} \mathrm{e}^{-\mathrm{i} h \mathcal{H}^Z} + \mathcal{O}\Big(h^2\Big)\,,$$

where

$$\mathcal{H}^{\alpha} = \mathbf{e}^{\top} \mathbb{S}^{\alpha} + \frac{1}{2} \mathbb{S}^{\alpha \top} \boldsymbol{C}^{\alpha, \alpha} \mathbb{S}^{\alpha}, \qquad \alpha \in \{X, Y, Z\},$$

and

$$\mathrm{e}^{-\mathrm{i}h\mathcal{H}^{\alpha}} = \prod_{\ell=1}^{n} \mathrm{e}^{-\mathrm{i}h\mathrm{e}_{\ell}^{\alpha}\alpha_{\ell}} \prod_{j=1}^{n} \prod_{k=j+1}^{n} \mathrm{e}^{-\mathrm{i}h\mathcal{C}_{j,k}^{\alpha,\alpha}\alpha_{j}\alpha_{k}},$$

computed exactly using *n* single-qubit gates and $O(n^2)$ coupling gates.



Trotterisation is one of the earliest candidates for Hamiltonian simulation.

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No good reason to use Trotter instead of Strang, even for NISQ

Chen, Foroozandeh, Budd & S. 2023. Quantum simulation of highly-oscillatory many-body Hamiltonians for near-term devices, submitted

 $\mathrm{e}^{h(A+B)} \approx \mathrm{e}^{a_1hB} \mathrm{e}^{b_1hA} \mathrm{e}^{a_2hB} \dots \mathrm{e}^{b_nhA} \dots \mathrm{e}^{a_2hB} \mathrm{e}^{b_1hA} \mathrm{e}^{a_1hB}$

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Kreusser, Lockyer, Müller, & S 2024. Learning efficient and provably convergent splitting methods

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(Polynomial) Krylov methods

Krylov subspace

$$\mathcal{K}_m(A, u_0) = \operatorname{span}\{u_0, Au_0, \ldots, A^{m-1}u_0\}$$

with basis \mathcal{V}_m and tridiagonal \mathcal{H}_m has super-linear accuracy,

$$\left\|\mathrm{e}^{A} u_{0} - \mathcal{V}_{m} \mathrm{e}^{\mathcal{H}_{m}} \mathcal{V}_{m}^{*} u_{0}\right\| \leq C \left(\frac{\mathrm{e}\rho}{2m}\right)^{m}$$

conserves norm and energy but not unitarity.



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accurate once $m \ge \rho = ||A||$, is surpassed (Hochbruck & Lubich 1997). High accuracy for small steps, but ineffective for large steps.

Shift-and-Invert (Sal) method

$$\mathcal{Q}_m(A, u_0) = \mathcal{K}_m((A - \alpha I)^{-1}, u_0),$$

is equivalent to Polynomial Krylov with shift-inverted matrix $(A-lpha I)^{-1}$ and

$$\underbrace{\mathrm{e}^{hA}}_{\varphi_{h}^{A}(u_{0})} \approx \underbrace{\mathcal{V}_{m}\mathrm{e}^{h(\alpha I - H_{m}^{-1})}\mathcal{V}_{m}^{*}u_{0}}_{\Phi_{h}^{A}(u_{0}, \alpha)}$$

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How should we choose the shift α ? Learning (Botchev, Grimm & M. Hochbruck 2013, Katrutsa, Botchev, & Oseledets 2019), Rational Krylov fitting (Berljafa & Güttel 2017)

Optimise an approximation of the local error:

$$\underbrace{\left\|\varphi_{h}^{A}(u_{n})-\Phi_{h}^{A}(u_{n},\alpha_{n})\right\|}_{\text{true local error }\mathcal{L}(h,u_{n},\alpha)} \propto \underbrace{\left\|\partial_{t}\Phi_{h}^{A}(u_{n},\alpha_{n})-A\Phi_{h}^{A}(u_{n},\alpha_{n})\right\|}_{\text{defect based estimate of local error }L(h,u_{n},\alpha)}$$

$$\alpha_n^* = \operatorname{argmin}_{\alpha \in \Omega} L(h, u_n, \alpha)$$

adaptive (i.e., on-the-fly), unsupervised approach.

energy not conserved, error estimate asymptotic and expensive.

$$\mathcal{Q}_m(A, u_0) = \mathcal{K}_m((A - \alpha I)^{-1}, u_0),$$

Rayleigh quotient:

$$A_m = \mathcal{V}_m^* A \mathcal{V}_m$$

The Rayleigh approximation:

$$\mathrm{e}^{hA} \mathbf{v} \approx \beta \mathcal{V}_m \mathrm{e}^{hA_m} \mathcal{V}_m^* u_0.$$

Optimise an approximation of the local error:

$$\frac{\left\|\varphi_{h}^{A}(u_{n})-\Phi_{h}^{A}(u_{n},\alpha_{n})\right\|}{\text{true local error }\mathcal{L}(h,u_{n},\alpha)} \leq \underbrace{C\int_{0}^{h}\left|e_{m}^{*}H_{m}^{-1}e^{sA_{m}}e_{1}\right|\,\mathrm{d}s}_{\text{integral estimate of local error }L(h,u_{n},\alpha)}$$

$$\alpha_n^* = \operatorname{argmin}_{\alpha \in \Omega} L(h, u_n, \alpha)$$

adaptive (i.e., on-the-fly), unsupervised approach. energy conserved, error estimate not asymptotic

$$\mathcal{Q}_m(A, u_0) = \mathcal{K}_m((A - \alpha I)^{-1}, u_0),$$

Rayleigh quotient:

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adaptive (i.e., on-the-fly), unsupervised approach.

energy conserved, error estimate not asymptotic , but expensive?

In practice, both Shift-and-Invert and Rayleigh quotion approaches work well with cheaper surrogates



Tennyson, Jawecki, Dolgov, & S., 'Optimal poles for the Shift-and-Invert method', in preparation

$$e^{ix} \approx f(ix), \quad x \in \sigma(H)$$

Then we have good approximation of the matrix exponential,

$$e^{-itH} = U \operatorname{diag}\left(e^{-itE_k}\right) U^{-1} \approx U \operatorname{diag}(f(itE_k)) U^{-1} = f(itH)$$

	Asymptotic	Approximate e ^z on spectrum
	z ightarrow 0	$z \in [a, b] \subseteq \sigma(A)$
	Taylor	Chebyshev
Polynomial	$\sum_{k=0}^{n} \frac{z^k}{k!}$	$J_0(i) + 2 \sum_{k=1}^{n} i^k J_k(-i) T_k(z)$
Rational	$\frac{Padé}{\frac{1+\frac{1}{2}z+\frac{1}{12}z^2}{1-\frac{1}{2}z+\frac{1}{12}z^2}}$?

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- Cannot conserve unitarity, norm, energy.
- May have stability issues (due to noise outside spectrum).

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AAA & AAA–Lawson (Nakatsukasa, Sète & Trefethen 2018, Nakatsukasa & Trefethen 2020) are greedy algorithms for rational approximations (i.e. fitting) based on the Loewner matrix framework.



Loewner matrix based rational approximations and interpolations are unitary (to machine precision when using a modified AAA/AAA–Lawson algorithm).

Jawecki & S 2023. Unitarity of some barycentric rational approximants, IMA J. Num. Anal.

Includes Antoulas & Anderson 1986, Mayo & Antoulas 2007, NST 2018 (AAA), NT 2020 (AAA–Lawson), JS (*submitted*) (interpolation at Chebyshev nodes, modified BRASIL algorithm, modified AAA–Lawson), ...

Theorem. For $\omega \in (0, (n+1)\pi)$, there exists a unique unitary best approximation $r \in U_n$, i.e.,

$$\|r - \exp(\omega \cdot)\| = \inf_{u \in \mathcal{U}_n} \|u - \exp(\omega \cdot)\|, \qquad \|f\| := \sup_{x \in [-1,1]} |f(\mathbf{i}x)|$$

whose phase error equioscillates at 2n + 2 points, where max approx error is achieved. Moreover, r has minimal degree n, and distinct poles.

Three new algorithms: Interpolation at Chebyshev points, modified AAA–Lawson and BRASIL. Superlinear convergence, A-stability, Time-symmetry





C. Moler & C. V. Loan, Nineteen Dubious Ways to Compute the Exponential of a Matrix,

Twenty-Five Years Later, SIAM Review (2003).

	Asymptotic	Approximate e^z on spectrum	Iterative
	z ightarrow 0	$\pmb{z} \in [\pmb{a}, \pmb{b}] \subseteq \sigma(\pmb{A})$	Use A and u_0
	Taylor	Chebyshev	
Polynomial	$\sum_{k=0}^{n} \frac{z^{k}}{k!}$	$J_0(i) + 2 \sum_{k=1}^{n} i^k J_k(-i) T_k(z)$	Lanczos
	Padé		
Rational	$\frac{1\!+\!\frac{1}{2}z\!+\!\frac{1}{12}z^2}{1\!-\!\frac{1}{2}z\!+\!\frac{1}{12}z^2}$	unitary best approximations	Rational Krylov

Other techniques: Diagonalisation & Spectral methods, Scaling and Squaring, Splitting

AAA [NST 18], AAA–Lawson [NT 20], their unitary modifications [JS 23], and three new algorithms [JS submitted].

- Jawecki & S. 2023. Unitarity of some barycentric rational approximants, IMA J. Num. Anal.
- Jawecki & S. 2023. Unitary rational best approximations to the exponential function, submitted.
- Jawecki & S., in preparation.

Outline

Hamiltonian Simulation

$$\mathrm{i}\partial_t\psi\ =\ \mathrm{H}(\psi,t)\,\psi,\qquad \psi(t)\in\mathscr{H}.$$

1. Linear

2. Driven

 $\partial_t u = A u$ $\partial_t u = A(t) u$

3. Non-linear

 $\partial_t u = \mathbf{A}u + \mathbf{N}(u)$

Driven systems

The solution to u'(t) = A(t)u(t) can be approximated by

• Autonomisation (Sanz-Serna & Portillo 1996), if A(t) = B(t) + C

$$u_{n+1} = \left(\prod_{k=1}^{s} \mathrm{e}^{b_k h \mathcal{B}(\boldsymbol{\tau}_k)} \mathrm{e}^{c_k h C}\right) u_n, \qquad \boldsymbol{\tau}_{k+1} = \boldsymbol{\tau}_k + c_k h, \quad \boldsymbol{\tau}_0 = t_n,$$

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• Commutator-free (Alvermann & Fehske 2011)

$$\exp(\Theta) \approx \exp\left(\sum_{k=1}^n c_{1k} h A(t_k)\right) \dots \exp\left(\sum_{k=1}^n c_{pk} h A(t_k)\right).$$

Blanes, Casas & Thalhammer 2017, Rational extension (S. Maslovskaya, Offen, Ober-Blöbaum, S. & Wembe 2024, Commutator-free Cayley methods, *submitted*)

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• Magnus expansion (Magnus 1954)

$$u(h) = \exp(\Theta(h)) u_0, \qquad \Theta(h) = \int_0^h A(\xi) \, \mathrm{d}\xi - \frac{1}{2} \int_0^h \int_0^{\xi} [A(\zeta), A(\xi)] \, \mathrm{d}\zeta \, \mathrm{d}\xi + \mathcal{O}\left(h^5\right)$$

Magnus-Krylov (Kormann, Holmgren & Karlsson 2008, Iserles, Kropielnicka, & S. 2018, SINUM), Magnus-Zassenhaus (IKS 2016, Proc. Roy. Soc. A, IKS 2019a, J. Comput. Phys.), Magnus-Splittings for laser-matter (IKS 2019a, Comput. Phys.) Commun., S. 2019c, J. Chem. Phys.)

Is Magnus expansion DoA for quantum algorithms?

$$A(t) = -\mathrm{i}H(t), \quad H(t) = \sum_{k=1}^{n} \sum_{\alpha \in \{X, Y, Z\}} \mathrm{e}_{k}^{\alpha}(t) \, \alpha_{k} + \frac{1}{2} \sum_{j,k=1}^{n} \sum_{\alpha,\beta \in \{X, Y, Z\}} \boldsymbol{C}_{j,k}^{\alpha,\beta} \, \alpha_{j} \, \beta_{k}$$

A has $\mathcal{O}(|\mathcal{C}|) = \mathcal{O}(n^2)$ terms. Does $\int_0^h \int_0^{\xi} [A(\zeta), A(\xi)] d\zeta d\xi$ have $\mathcal{O}(|\mathcal{C}|^2) = \mathcal{O}(n^4)$ terms?

Instead, other approaches were developed: Dyson series (Kieferova et al. 2019), time-ordered operators (Watkins et al. 2022), L1 norm scaling (Berry et al. 2020), permutation expansion (Chen et al. 2021), slowly varying Hamiltonians (Haah et al. 2021), interaction picture (Low & Wiebe 2018), Floquet approach (Mizuta et al. 2023), Schrödingerization (Jin, Liu, Yu 2022)

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Chen, Foroozandeh, Budd & S. 2023. submitted

related: 2 controls Ikeda, Abrar, Chuang & Sugiura 2023, Quantum., commutator-free Casares, Zini & Arrazola

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$$u^{[k+1]} = e^{b_k h L} e^{c_k h g(u^{[k]}, \tau_k)} u^{[k]}, \qquad \tau_{k+1} = \tau_k + b_k h, \quad \tau_0 = t_n,$$
$$u_{n+1} = u^{[s]}, \qquad u^{[0]} = u_n$$

Related: dilation techniques such as Schrödingerization (Jin, Liu, Yu 2022)

• Exponential Integrators (Hochbruck & Ostermann 2000), A(u) = Lu + g(u)u,

$$u_{n+1} = e^{hL}u_n + L^{-1}(e^{hL} - I)g(u_n)u_n$$

not a geometric integrator

• Iterative linearisations

$$u^{[k+1]}(h) = \exp\left(\Theta^{[k]}(h)\right) u^{[k]},$$

$$\Theta^{[k]}(h) = \int_{0}^{h} A(u^{[k]}(\xi), \xi) \, \mathrm{d}\xi - \frac{1}{2} \int_{0}^{h} \int_{0}^{\xi} \left[A(u^{[k]}(\zeta), \zeta), A(u^{[k]}(\xi), \xi)\right] \, \mathrm{d}\zeta \, \mathrm{d}\xi + \mathcal{O}\left(h^{5}\right).$$
$$u_{n+1} = u^{[3]}, \qquad u^{[0]} = u_{n}$$

Chen, Iserles, Kropielnicka, & S. 2024, Computation of some dispersive equations through their iterated linearisation, submitted.

Takeaways

Hamiltonian Simulation is central to quantum computing

- early candidate for quantum supremacy
- has real-world applications
- is a building block for many quantum algorithms

Correspondence between Classical and Quantum algorithms

- Qubitization
 - achieves additive complexity, based on Chebyshev approximation
 - does not conserve unitarity, norm and energy; may have stability issues
- Unitary rational approximations (Padé, AAA, best approximation,...)
 - faster convergence, extremely stable, conserve unitarity, norm and energy
 - currently no quantum algorithm
- Machine learned Trotterisations (splittings)
 - convergence guarantees, conserve unitarity, norm and modified energy
 - allow long time-steps, low error constants
 - can they help create optimized cricuits?
 - can we do this in an unsupervised way?
- Magnus based methods work well for driven spin systems